

11E2210BS64

DINGS' MOTION
work order
DATE REV00

REVISION

REV.

DATE

DESCRIPTION

DRAWN BY

Sticker

 $L \pm 1$ 45 ± 0.5 1.5 ± 0.2

Label

 $\phi 22 \pm 0.05$ 4-M2.5 ∇ 2.5Min $\square 28$ $\square 23 \pm 0.15$ 320 ± 20
4leads
AWG#26 $\phi 21$ 4- $\phi 3.4$

16

17.2

8

 $\phi 14$ $\phi 27$

4

Notes,
1.To maximize output force and life of linear actuators,
radial load on lead screws should be avoided or be kept at a minimum.

Motor's phase	2
Step angle($\pm 5\%$)	1.8°
Rated current/phase	0.95 A(RMS)
Resistance/phase(20°C)	4.1 $\Omega \pm 10\%$
Inductance/phase(1V,1kHz)	4 mH $\pm 20\%$
Linear travel per step	0.03mm
Lead screw diameter	$\phi 6$ mm
Lead screw lead	6mm
Grade	C7 (DY)
Insulation class	B
Insulation resistance	100M Ω (500VDC)
Heat rise	80°C
Motor weight	0.17 Kg

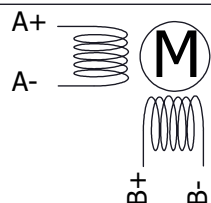
CUSTOMER

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WIRING CHART

EXCITATION SEQUENCE



CW	$\longrightarrow$			
Red A+	+		-	
Red/wht A-	-		+	
Grn B+		+		-
Grn/wht B-		-		+
CCW	$\longleftarrow$			

UNLESS OTHERWISE SPECIFIED ALL DIMENSIONS ARE IN MILLIMETERS AND TOLERANCES ARE AS BELOW PER ISO2768-ck.			
LINEAR		ANGULAR	
0 ~ 3	± 0.2	0 ~ 10	$\pm 15'$
3 ~ 6	± 0.5	10 ~ 50	$\pm 30'$
6 ~ 30	± 0.8	50 ~ 120	$\pm 1^\circ$
30 ~ 120	± 1.5	120 ~ 400	$\pm 1.5^\circ$

DRAWN

DATE

APPRVD

DATE

MODEL

11E2210BS64

DINGS'

SIZE	A3	SHEET	1 OF 1
SCALE	1 : 1	REV	00

